



SLR-2.0

An overview about the new SLR/LLR control software from Wettzell

FESG

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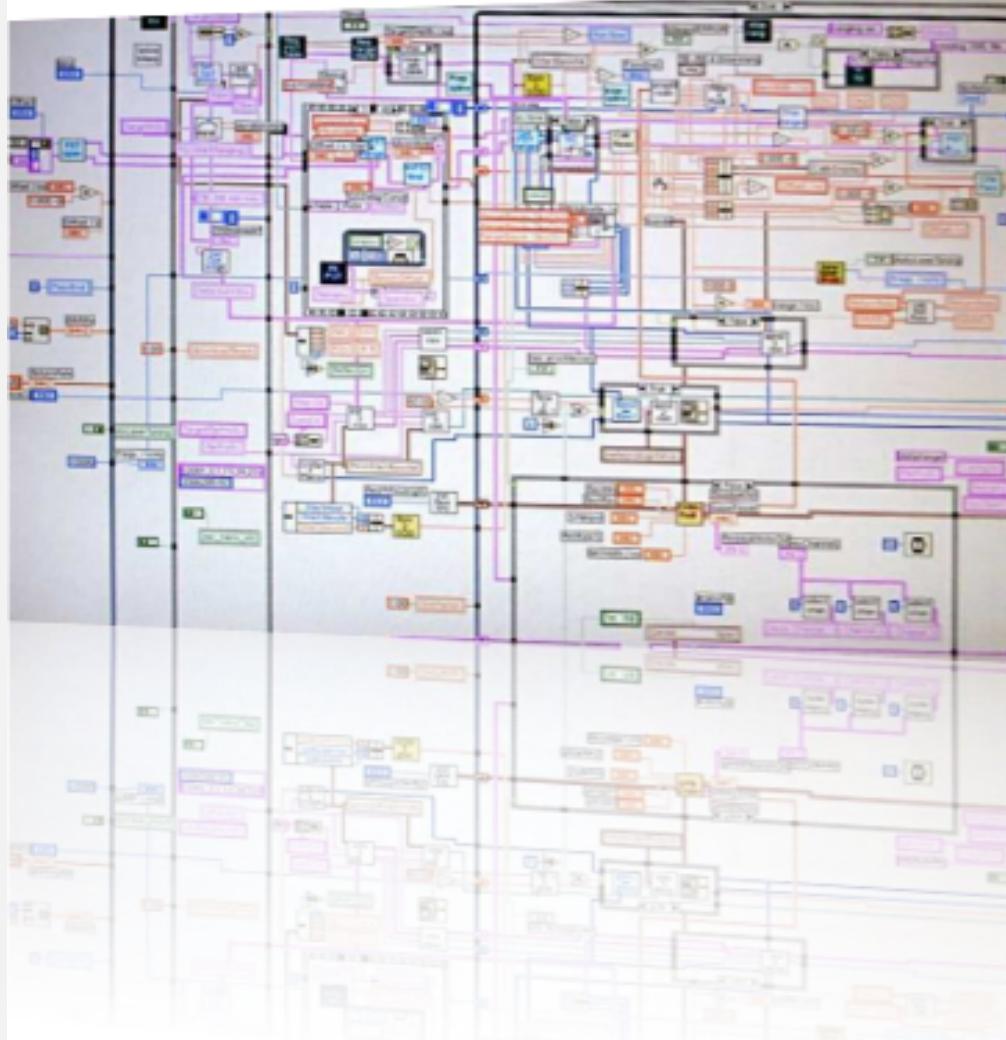
Bundesamt für
Kartographie und Geodäsie

**Neidhardt (TUM), Lauber (TUM), Mühlbauer (BGK),
Plötz(BGK), Leidig (TUM), Eckl (BKG), L.Schreiber (FH-Deggendorf),
Riederer (BKG), Dassing (BKG)**



SLR 1.0 (historically grown)

Lab View System

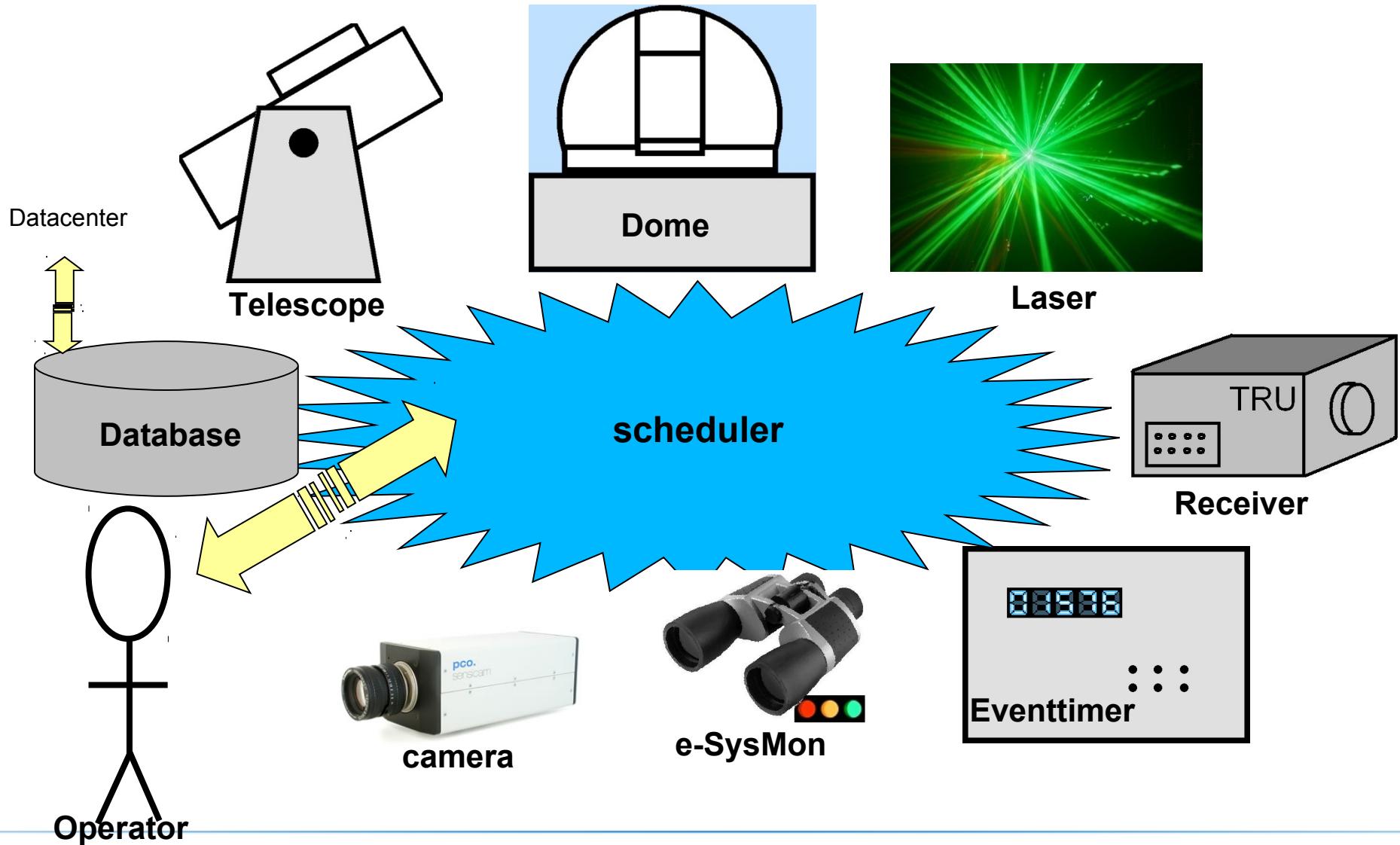


Issues:

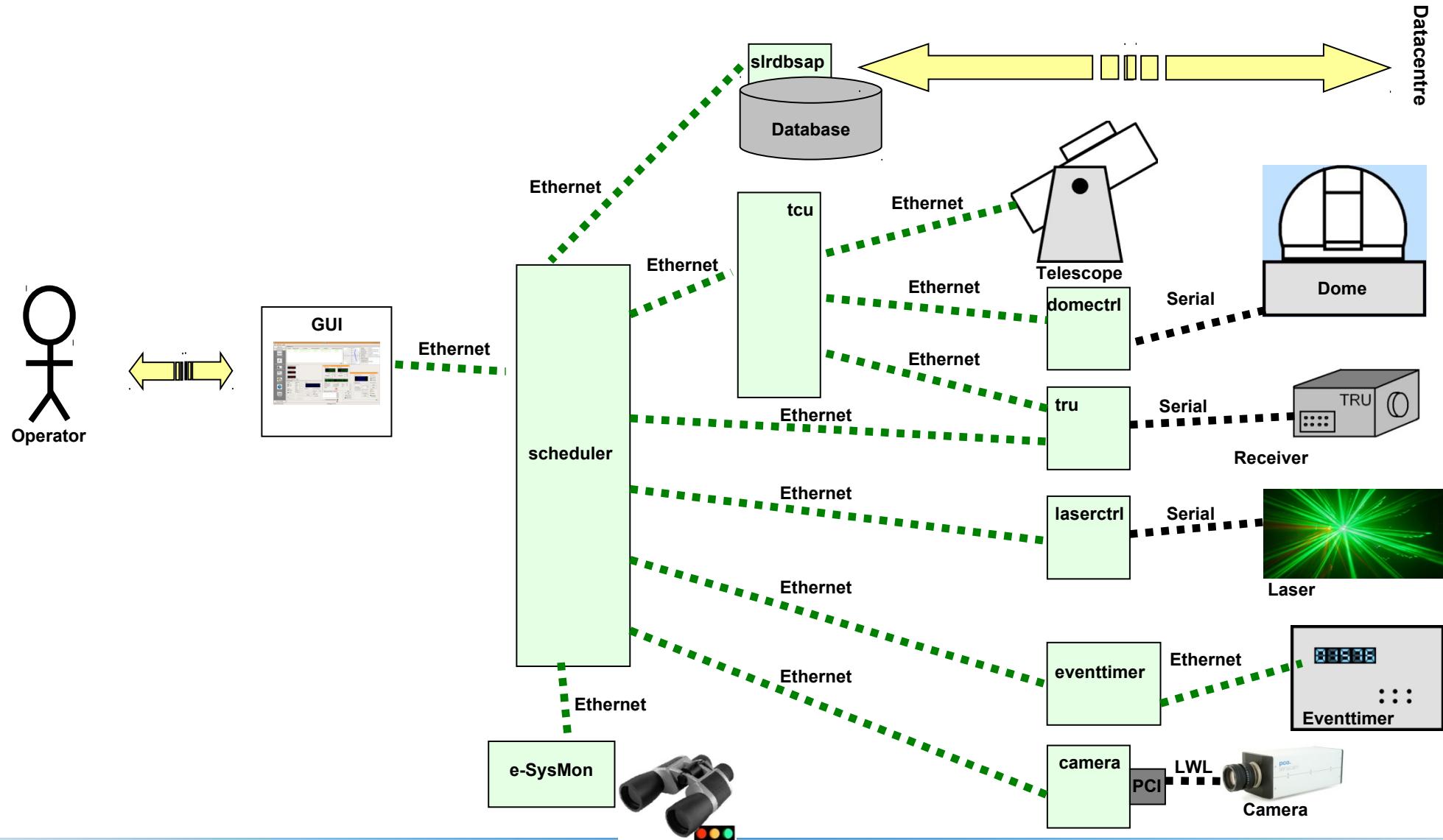
- old computer
- LabView 5.0
- upgrade?
- NI-card
(hardware)
- nearly no
documentation
- switching
between
satellites takes
too long

redesign

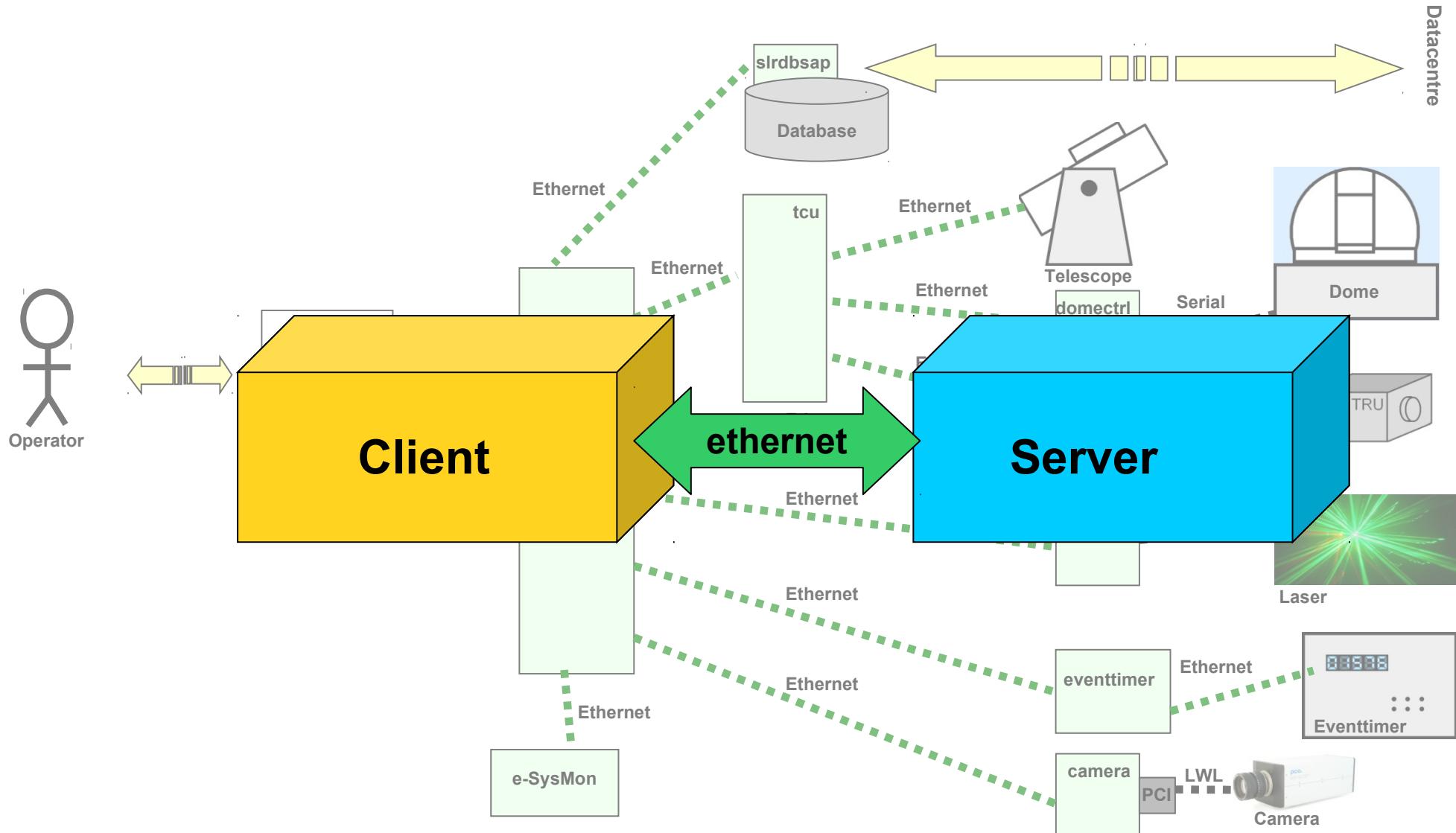
Decomposition into modules



Internal architecture

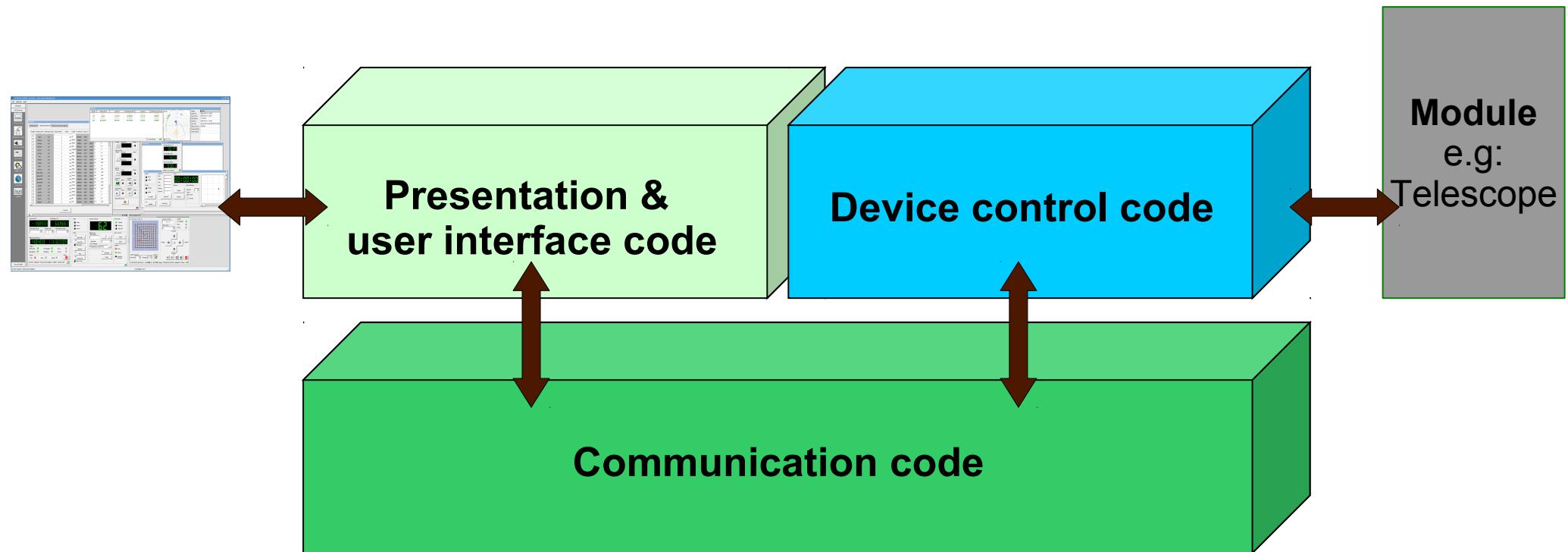


Hierarchical Structure





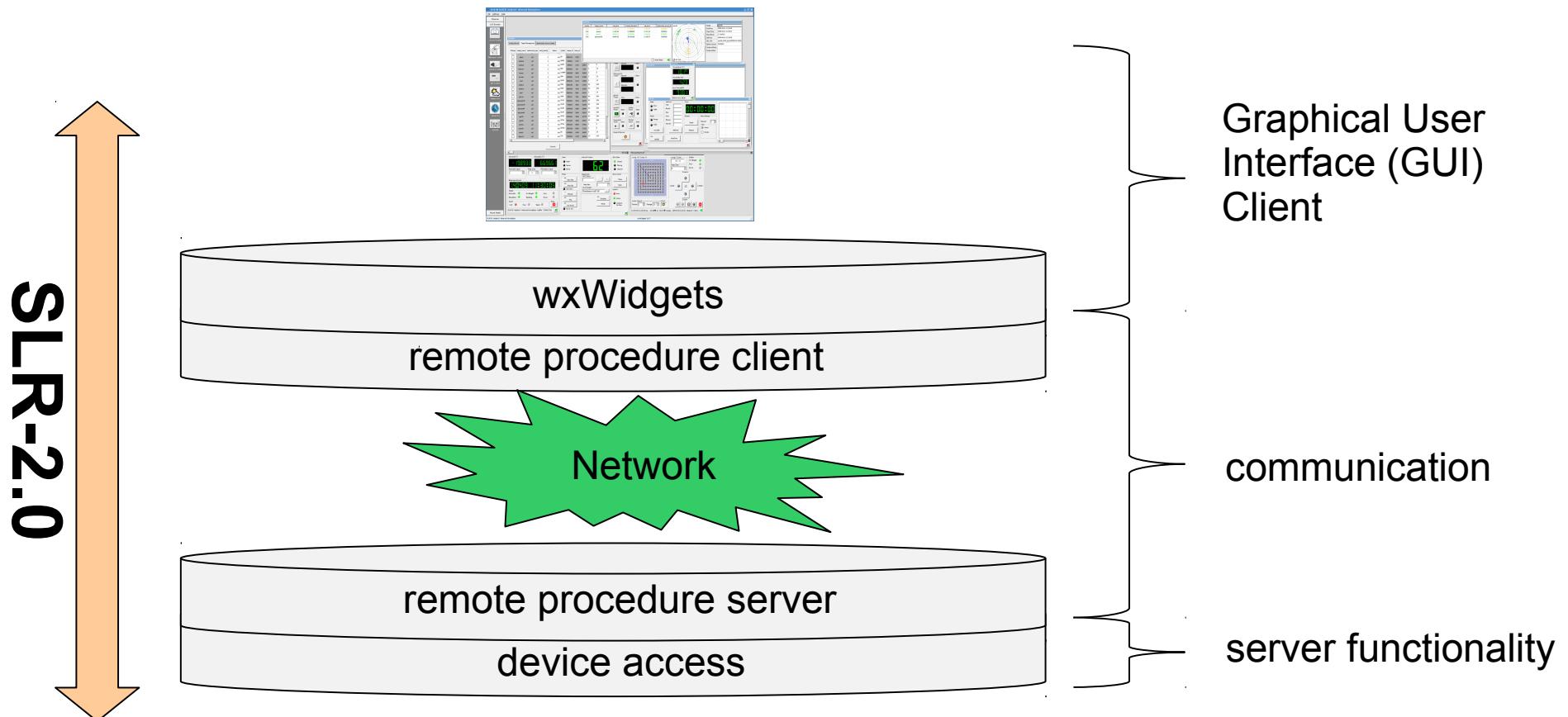
Separation of concerns



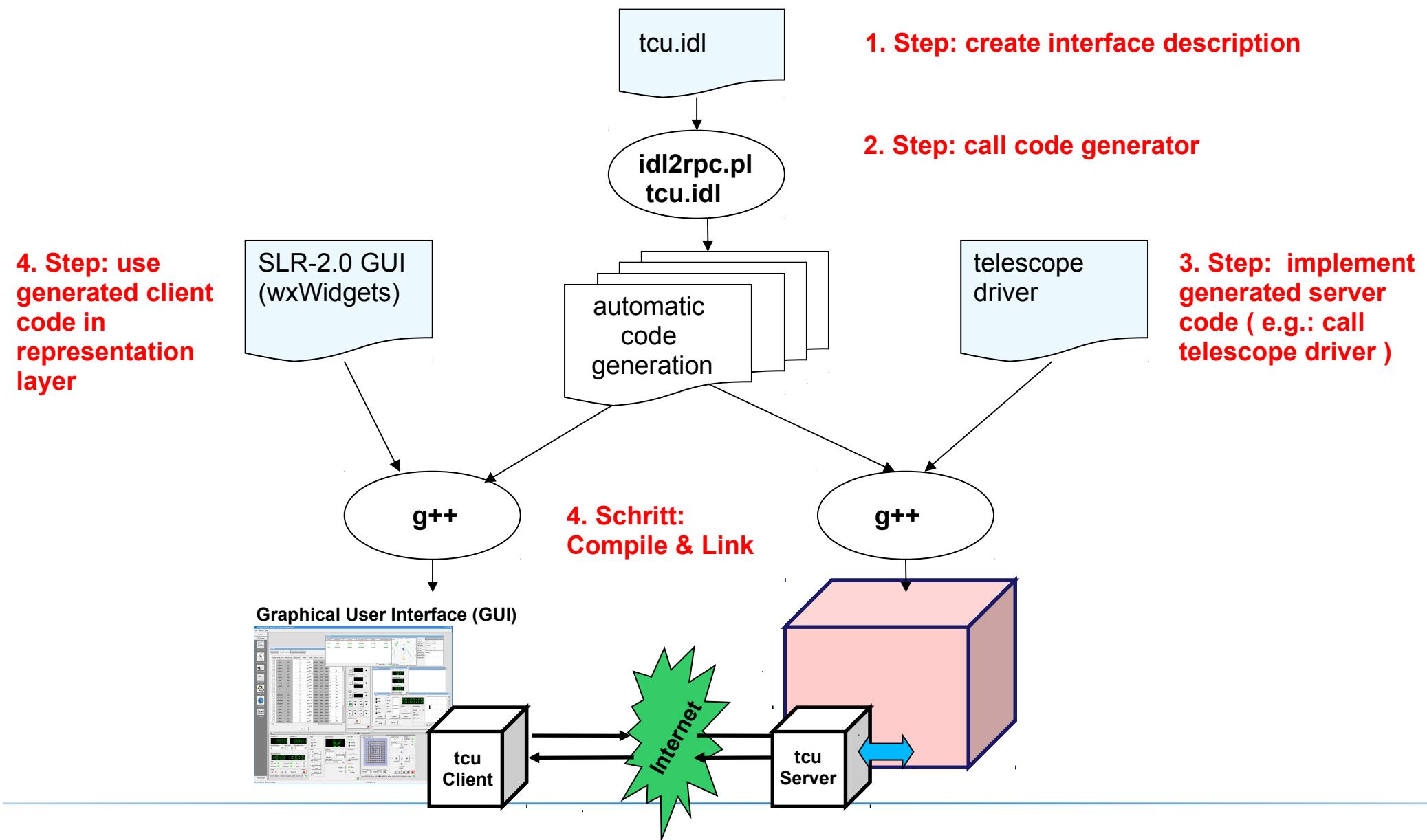
- strict separation between representation, processing and communication



Multiple Layers



RPC-Middleware, based on generic programming



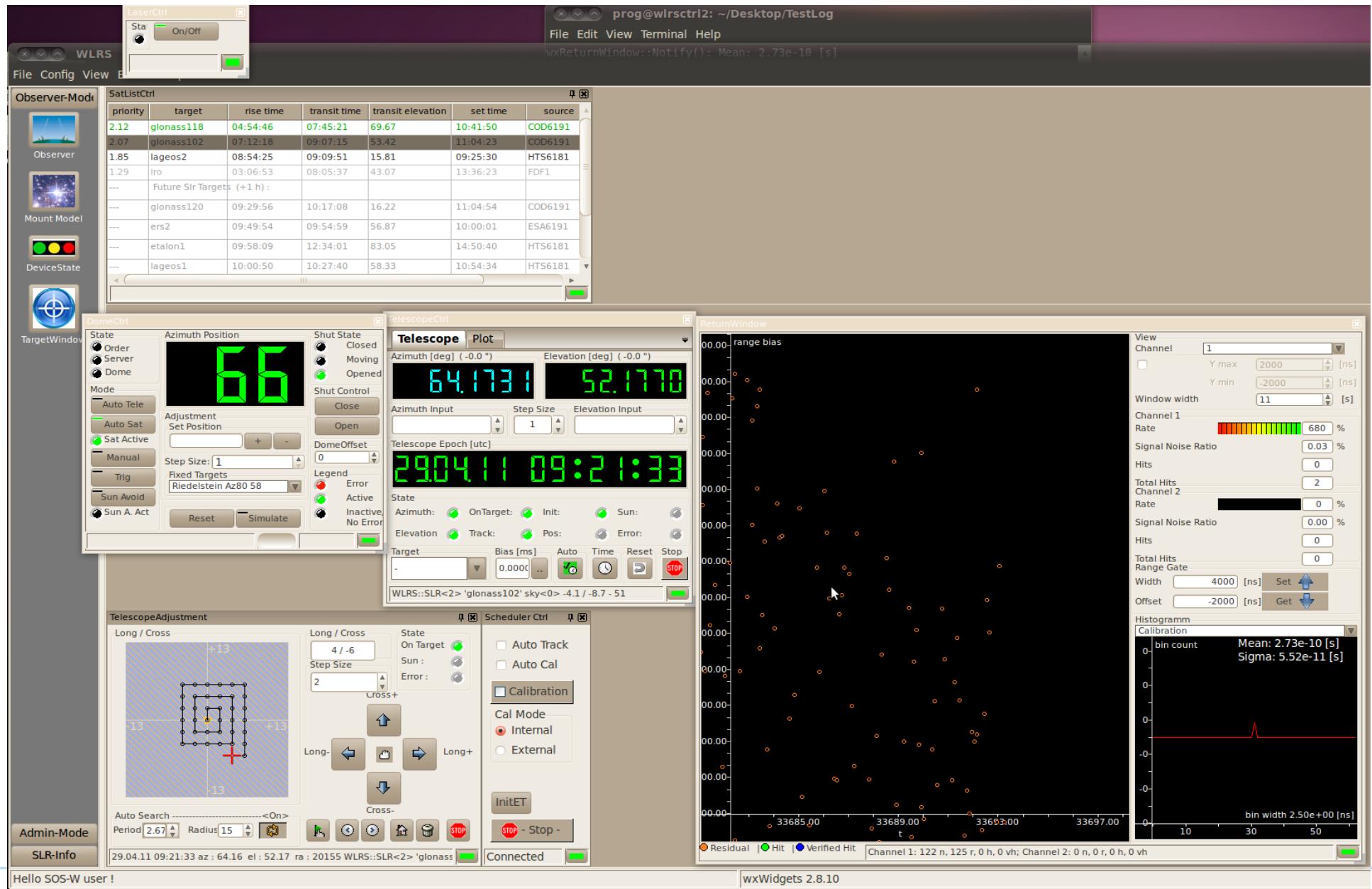


Main Goals

- individual and independent interfaces
- semi-automation
- extensible and flexible design
- standardized and reliable (poster nr. 47)
- based on low-level but well proven communication protocols
- generic programming techniques to avoid individual network programming
- open source, nearly no proprietary software dependencies
- ANSI – C/C++ compliant software
- works on old and new Linux systems (32/64-Bit)

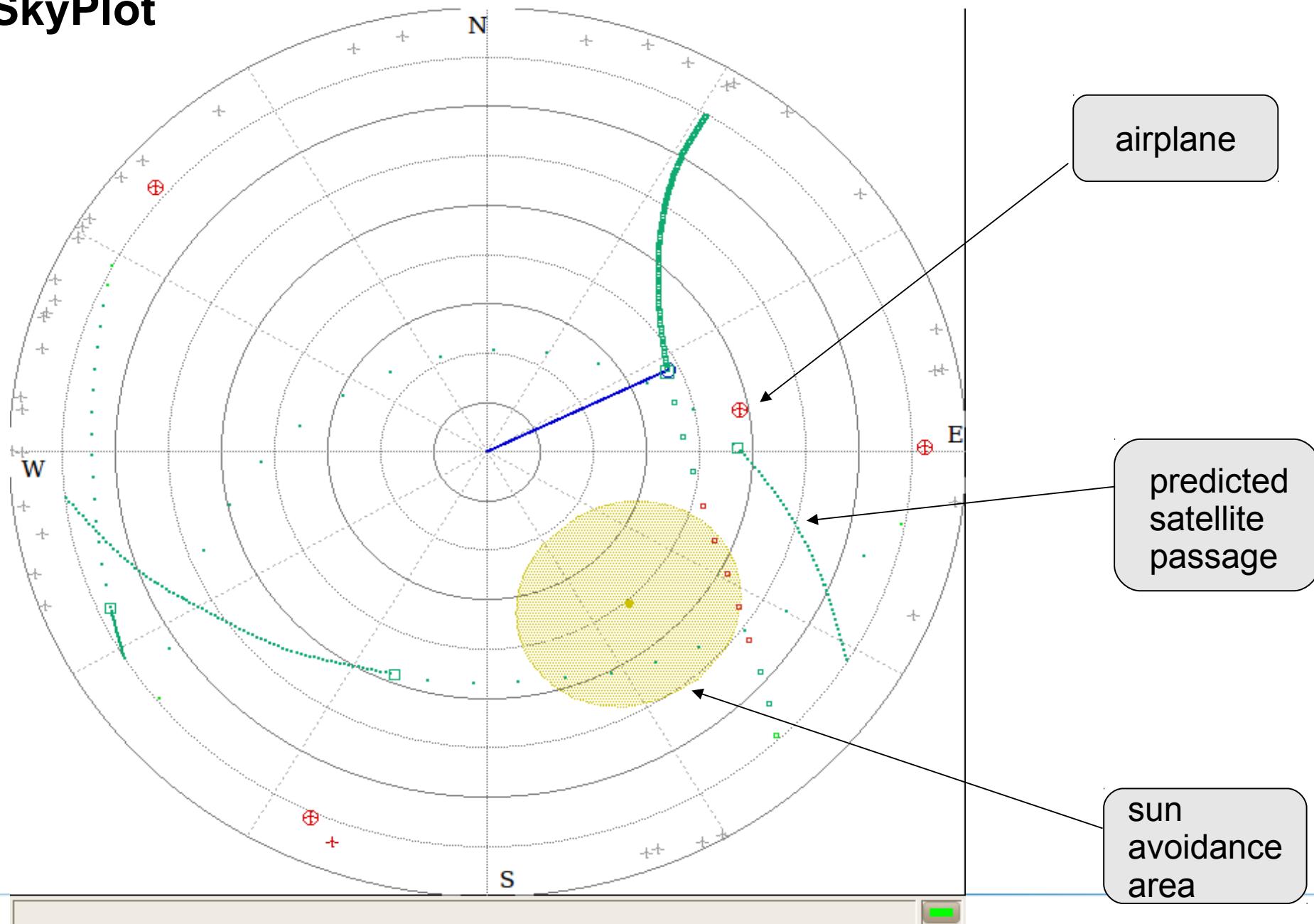


Graphical User Interface



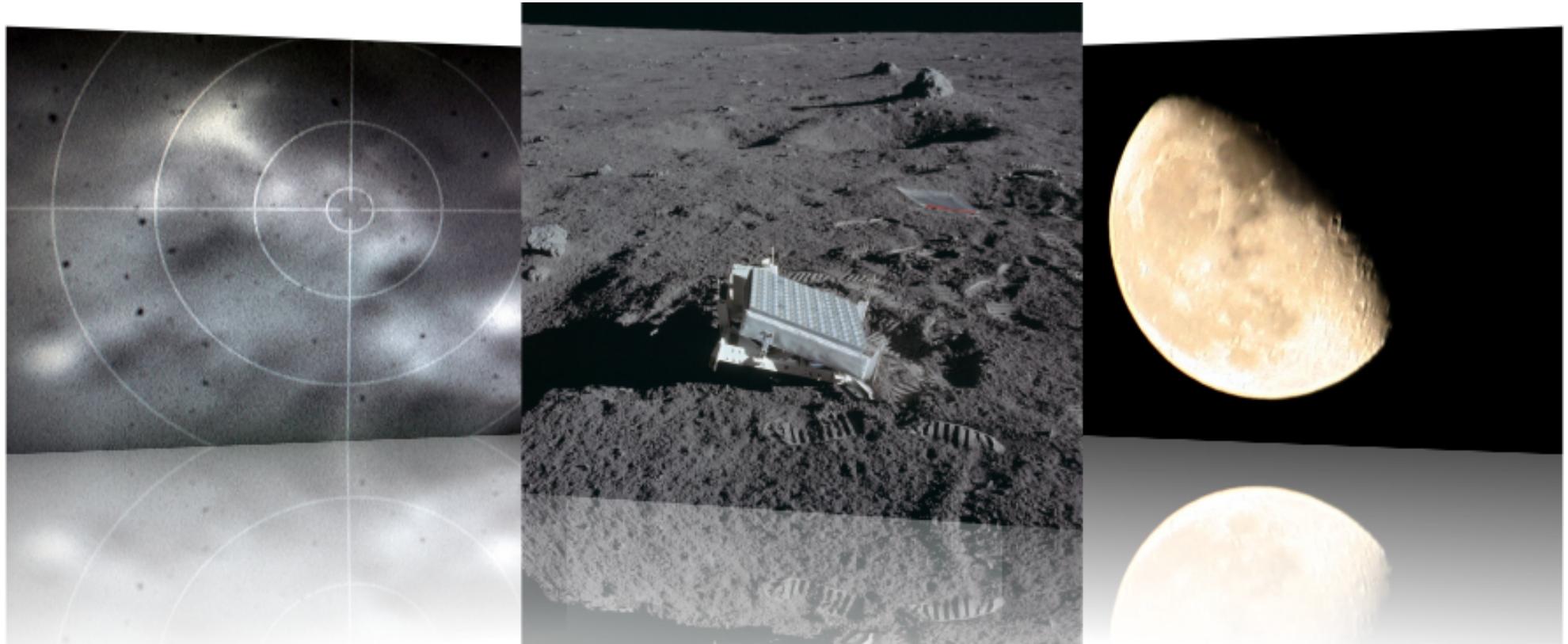


SkyPlot





On the way towards LLR observations

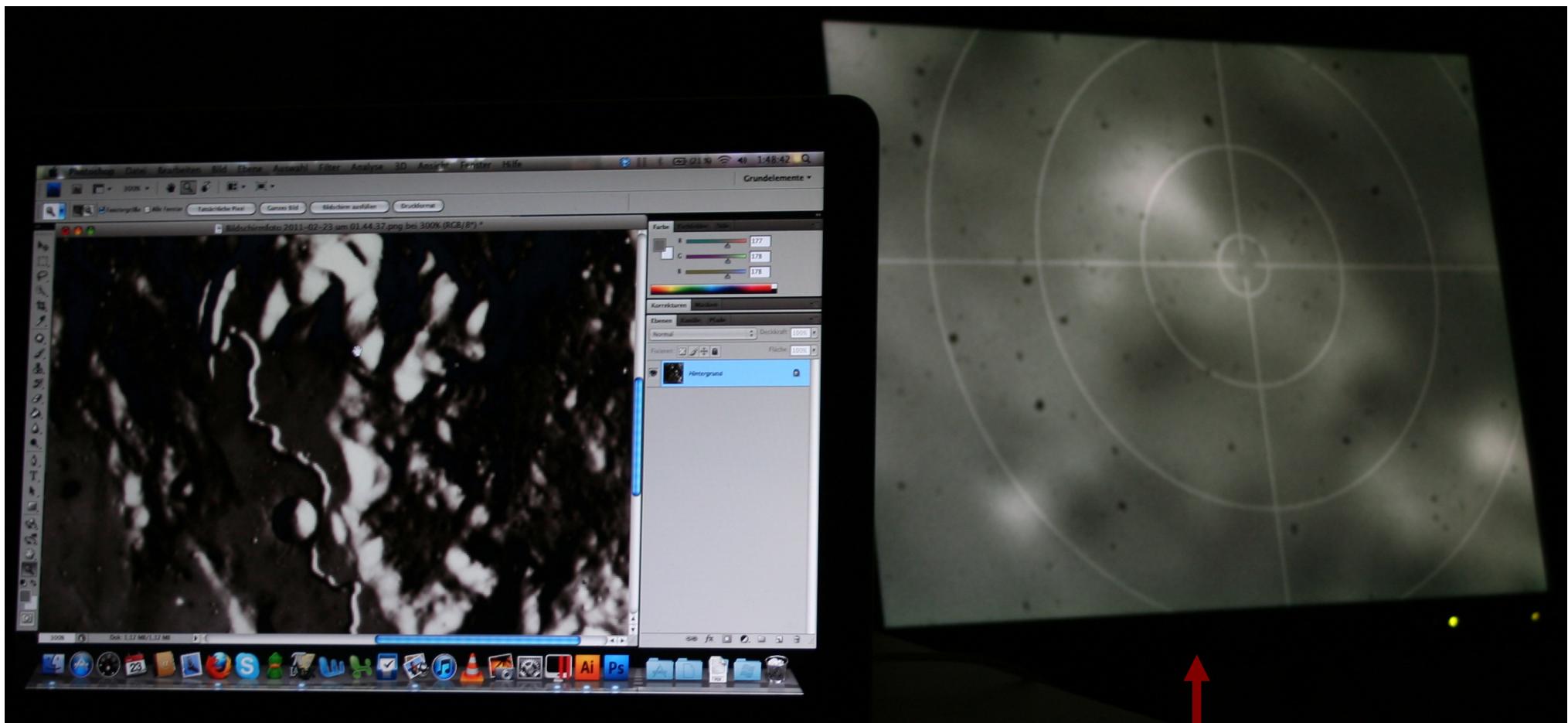


Diploma Thesis:

- comparison of LLR-prediction software (Grasse vs. Texas software)
- verification of Wettzell routines

Next steps:

- implement LLR observation mode in SLR 2.0



Apollo 15 seen from
Wettzell



Thank you!